Scaled and adjusted restricted tests in multi-sample analysis of moment structures *

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Abstract

We extend to score, Wald and difference test statistics the scaled and adjusted corrections to goodness-of-fit test statistics developed in Satorra and Bentler (1988a,b). The theory is framed in the general context of multisample analysis of moment structures, under general conditions on the distribution of observable variables. Computational issues, as well as the relation of the scaled and corrected statistics to the asymptotic robust ones, is discussed. A Monte Carlo study illustrates the comparative performance in finite samples of corrected score test statistics.

Keywords: Moment-structures, Goodness-of-fit test, score test, Wald test, scaling corrections, chi-square distribution, non-normality
1 Introduction

Moment structure analysis is widely used in behavioural, social and economi-
cic studies to analyse structural relations between variables, some of which
may be latent (i.e., unobservable); see, e.g., Bollen (1989), Yuan and Bentler
(1997), and references therein. Commercial computer programs to carry out
such analysis, for a general class of structural equation models, are availa-
bile (e.g., LISREL of Jöreskog and Sörbom, 1994; EQS of Bentler, 1995).
In multi-sample analysis, data from several samples are combined into one
analysis, making it possible, among other features, to test for across-group
invariance of specific model parameters. One issue which is central in mo-
ment structure analysis is the goodness-of-fit test of the model and the test
of restrictions on parameters.

Asymptotic distribution-free (ADF) methods which do not require distri-
bution assumptions on the observable variables have been developed (Bro-
wn, 1984; Muthén, 1989; Bentler, Lee and Weng, 1987). The ADF methods,
however, involve fourth-order sample moments, thus they may lack robust-
ness to small and medium-sized samples. In the case of non-normal data,
an alternative to the ADF approach is to use a normal-theory estimation
method in conjunction with asymptotic robust standard errors and test sta-
istics (see Satorra, 1992). Asymptotic robust test statistics may still lack
robustness to small and medium-sized samples. As an alternative to the
asymptotic robust test statistics, Satorra and Bentler (1994; Satorra and
Bentler, 1988a,b) developed a family of corrected normal-theory test statistics
which are easy to implement in practice, and which have been shown to
outperform the asymptotic robust test statistics in small and medium-sized
samples (e.g., Chou, Bentler and Satorra, 1991; Hu, Bentler and Kano, 1992;
Curran, West and Finch, 1996). Extension of Satorra-Bentler (SB)’s correc-
tions to goodness-of-fit test statistics in the case of the analysis of augmented
moment structures, multi-samples and categorical data, have been discussed
respectively by Satorra (1992, 1993) and Muthén (1993). In recent personal
communication, Bengt Muthén has kindly pointed to this author the need
to extend SB’s corrections to score and difference test statistics.

The purpose of the present paper is to extend SB's corrections to score
(Lagrange multiplier), difference and Wald test statistics. This is undertaken
in the general context of multi-sample analysis. We rely heavily on the
notation and results of Satorra (1989) and Satorra and Bentler (1994; Satorra
and Bentler, 1988a,b).

The chapter is structured as follows. In Section 2 we review the general theory of normal-theory GLS analysis of multi-sample moment structures, placing special emphasis on goodness-of-fit test statistics. The extension of the scaling and adjusted corrections to the restricted tests is undertaken in Section 3. Finally, Section 4 illustrates, by means of a Monte Carlo study, the finite sample size performance of competing score test statistics developed in Section 3.

2 Goodness-of-fit tests

Let \( \sigma \) and \( s \) be \( p \)-dimensional vectors of population and sample moments respectively, with

\[
\sqrt{n}(s - \sigma^0) \xrightarrow{L} \mathcal{N}(0, \Gamma),
\]

where \( \sigma^0 \) is the probability limit of \( s \), as sample size \( n \to +\infty \), \( \Gamma \) is the asymptotic variance matrix of \( \sqrt{n} s \), and “\( \xrightarrow{L} \)” denotes convergence in distribution as \( n \to \infty \). Consider a moment structure for \( \sigma \), \( \sigma = \sigma(\theta) \), where \( \sigma(\cdot) \) is a twice-continuously differentiable vector-valued function of a \( q \)-dimensional parameter vector \( \theta \in \Theta \), a compact subset of \( \mathbb{R}^q \). Let \( \hat{\theta} \) be an estimator of \( \theta \) that satisfies

\[
\sqrt{n}(\hat{\theta} - \theta_0) = O_p(1),
\]

with \( \theta_0 \) in the interior of \( \Theta \). The usual notation of stochastic orders of magnitude is used, i.e., \( O_p(1) \) and \( o_p(1) \) denote, respectively, “bounded” and “tends to zero in probability”, as \( n \to +\infty \). Usually, (2) is fulfilled whenever \( \sigma = \sigma(\theta) \) is locally identified (viz., the function \( \sigma(\theta) \) is injective in a neighbourhood of the true parameter value). Denote \( \hat{\sigma} := \sigma(\hat{\theta}) \) and \( \sigma_0 := \sigma(\theta_0) \).

It is assumed that \( \sqrt{n}(\hat{\theta} - g(s)) = o_p(1) \), where \( g(\cdot) \) is a \( q \)-dimensional continuously differentiable vector-valued function of \( s \), with \( g(\cdot) \) Fisher-consistent for \( \theta \), i.e. \( g(\sigma(\theta)) = \theta \), \( \theta \in \Theta \). The theory discussed involves the use of the Jacobian matrices \( \Xi := (\partial / \partial s') g(s) \) and \( \Delta := (\partial / \partial \theta') \sigma(\theta) \), which will be assumed to be regular at \( \sigma_0 := \sigma(\theta_0) \) and \( \theta_0 \) respectively. Note that Fisher-consistency of \( g(s) \) implies that \( \Xi \Delta = I_q \). In the developments that follow, \( \Delta \) and \( \Xi \) denote the corresponding matrices evaluated at \( \theta_0 \) and \( \sigma_0 \) respectively.

The above mentioned properties for \( \hat{\theta} \) are satisfied by most of the estimators commonly in use in moment structure analysis. In particular, they
are satisfied by the ML and GLS estimators discussed below. They are also satisfied in the case of instrumental variable estimators (e.g., Satorra and Bentler 1991).

A Wald-type statistic for testing the goodness-of-fit of the model can be developed. Since

\[ \sqrt{n}(s - \hat{\sigma}) = \sqrt{n}(s - \sigma^0) + \sqrt{n}(\hat{\sigma} - \sigma_0) - \sqrt{n}(\hat{\sigma} - \sigma_0), \]

a Taylor series expansion of \( \sqrt{n}(\hat{\sigma} - \sigma_0) \) at \( \sigma_0 \), gives

\[ \sqrt{n}(s - \hat{\sigma}) = \sqrt{n}(s - \sigma^0) + \sqrt{n}(\sigma^0 - \sigma_0) - \Delta \sqrt{n}(\hat{\theta} - \theta_0) + o_p(1), \]

which combined with (1) yields

\[ \sqrt{n}(s - \hat{\sigma}) \overset{L}{\to} \mathcal{N}(\tau, H), \quad (3) \]

where

\[ \tau := \lim_{n \to +\infty} \sqrt{n}(\sigma^0 - \sigma_0) \quad (4) \]

and

\[ H := (I - \Delta \Xi)\Gamma'(I - \Delta \Xi)', \quad (5) \]

We further assume

\[ \tau = \lim_{n \to +\infty} \sqrt{n}(\sigma^0 - \sigma_0) < +\infty, \]

which is the usual assumption of a sequence of local alternatives (needed to ensure finite asymptotic distribution of test statistics when the model is not exactly true).

Let \( \Delta_\perp \) be an orthogonal complement of \( \Delta \), i.e., \( \Delta_\perp \) is a \( p \times (p - q) \) matrix of full-column rank such that \( \Delta_\perp'\Delta = 0 \). From (3), we have

\[ \sqrt{n}\Delta_\perp'(s - \hat{\sigma}) \overset{L}{\to} \mathcal{N}(\Delta_\perp'\tau, \Delta_\perp'\Gamma\Delta_\perp), \quad (6) \]

since \( \Delta_\perp'\Delta_\perp = \Delta_\perp'\Gamma\Delta_\perp \), as \( \Delta_\perp'(I - \Delta G) = \Delta_\perp' \); hence, a residual-based goodness-of-fit test for the model is defined as the Wald-test statistic

\[ T_R = n(s - \hat{\sigma})'\hat{\Delta}_\perp\hat{\Delta}_\perp'(\hat{\Delta}_\perp'\hat{\Gamma}\hat{\Delta}_\perp)'\hat{\Delta}_\perp(s - \hat{\sigma}), \quad (7) \]

where \( \hat{\Delta}_\perp \) and \( \hat{\Gamma} \) are consistent estimators of \( \Delta_\perp \) and \( \Gamma \), respectively. The matrix \( \hat{\Delta}_\perp \) will be taken to be an orthogonal complement of \( \hat{\Delta} \), the matrix
$\Delta$ evaluated at the estimated value $\hat{\theta}$. Clearly, from the standard theory of Wald-test statistics (e.g., Moore, 1977), $T_R$ is asymptotically chi-square distributed with degrees of freedom $r := \text{rank } \Delta'_\perp \Gamma \Delta_\perp$ and non-centrality parameter $\lambda := \tau' \Delta'_\perp (\Delta'_\perp \Gamma \Delta_\perp)^+ \Delta'_\perp \tau$. When $\hat{\Gamma}$ is non-singular, we have

$$T_R = n(s - \hat{\sigma})' (\hat{\Gamma}^{-1} - \hat{\Gamma}^{-1} \Delta (\Delta' \hat{\Gamma}^{-1} \Delta)^{-1} \Delta' \hat{\Gamma}^{-1}) (s - \hat{\sigma}),$$

(8)

When $\hat{\Gamma}$ is the (distribution-free) consistent estimator of $\Gamma$ in (10) below, then $T_R$ will be called the asymptotic robust goodness-of-fit test statistic, since it is an asymptotic chi-square statistic regardless of the distribution of $z$. In the context of single-sample covariance structure analysis, this statistic was first introduced by Browne (1984). Its performance was studied by Yuan and Bentler (1998), and found to be adequate only in very large samples.

Consider now multi-sample data from $G$ population or groups, i.e., let $\{z_{gi}\}_{i=1}^{n_g}, g = 1, \ldots, G$, where it is assumed that, for each group $g$, the $z_{gi}$ are independent and identically distributed $p_g$-dimensional vectors of observable variables, with finite fourth-order moments. Define $\Sigma_g := E z_{gi}z_{gi}'$, and let the multi-sample vectors $\sigma$ and $s$ of population and sample moments, respectively, be given as $\sigma := (\sigma_1', \ldots, \sigma'_G)'$ and $s := (s_1', \ldots, s'_G)'$, where $\sigma_g' := \text{vec } \Sigma_g$, $s_g' = \text{vec } S_g$, with

$$S_g := \frac{1}{n_g} \sum_{i=1}^{n_g} z_{gi}z_{gi}'.
$$

Here “vec” denotes the column-wise vectorisation operator (see Magnus and Neudecker, 1999, for full details on this operator). Clearly, when there is independence across samples, the asymptotic variance matrix of $\sqrt{n} s$ is of the form

$$\Gamma = \text{block diag}(\frac{n_1}{n}, \ldots, \frac{n_G}{n}),$$

(9)

where $\Gamma_g$ is the asymptotic variance of $\sqrt{n_g} s_g$. We further assume that the matrices $S_g$ and $\Sigma_g$ are positive definite, and that $n_g/n \to f_g > 0$, as $n \to +\infty$ ($g = 1, \ldots, G$); in this case, a distribution-free consistent estimator of $\Gamma$ is

$$\hat{\Gamma} := \text{block diag}(\frac{n}{n_1} \hat{\Gamma}_1, \ldots, \frac{n}{n_G} \hat{\Gamma}_G),$$

(10)

where

$$\hat{\Gamma}_g := \frac{1}{n_g - 1} \sum_{i=1}^{n_g} (d_{gi} - s_g)(d_{gi} - s_g)',$$

(11)
with \( d_{ji} := \text{vec } z_{ji} z_{ji}' \).

We consider the generalised least-square (GLS) estimation method with normality as a working assumption; viz., the estimator \( \hat{\theta} \) is defined as the minimiser over the parameter space \( \Theta \) of the fitting function

\[
F_{GLS}(\theta) := (s - \sigma)' V (s - \sigma),
\]

with

\[
\hat{V} := \text{block diag}(\frac{n_1}{n} \hat{V}_1, \ldots, \frac{n_G}{n} \hat{V}_G)
\]

(12)

and \( \hat{V}_g = \frac{1}{2}(S_g^{-1} \otimes S_g^{-1}) \); clearly, \( F_{GLS}(\theta) = \frac{1}{2} \sum_{g=1}^{G} \frac{n_g}{n} \text{tr} \{(S_g - \hat{\Sigma}_g)S_g^{-1}\}^2 \). For single-sample covariance structure analysis, this method of estimation was first proposed by Browne (1974). When in the minimization process the matrices \( S_g \) in (12) are replaced iteratively by the fitted \( \hat{\Sigma}_g \), the so-called normal-theory reweighted GLS estimates are obtained.

Differentiation with respect to \( \theta \) yields the following first-order condition for the estimator \( \hat{\theta} \):

\[
(s - \hat{\sigma})' \hat{V} \hat{\Delta} = 0, \quad \left( \sum_{g=1}^{G} \frac{n_g}{n} (s_g - \hat{s}_g)' \hat{V}_g \hat{\Delta}_g = 0 \right).
\]

(13)

A related estimation method which is asymptotically equivalent to normal-theory GLS, and which produces estimators numerically equal to the re-weighted GLS estimators, is pseudo-ML estimation; viz., \( \hat{\theta} \) is the minimiser over \( \Theta \) of

\[
F_{ML}(\theta) = \sum_{g=1}^{G} \frac{n_g}{n} F_{ML}^{(g)}(\theta),
\]

with

\[
F_{ML}^{(g)}(\theta) := \ln | \Sigma_g | + \text{tr } S \Sigma_g^{-1} - \ln | S_g | - p^*_g,
\]

and \( p^*_g \) denoting the dimension of the \( z_{gi} \).

A goodness-of-fit test statistic associated with GLS estimation is defined as \( T_{GLS} := n F_{GLS}(s, \hat{\sigma}) \), which, using (13), can be written as

\[
T_{GLS} = (s - \hat{\sigma})' \left( \hat{V} - \hat{V} \hat{\Delta} (\hat{\Delta}' \hat{V} \hat{\Delta})^{-1} \hat{\Delta}' \hat{V} \right) (s - \hat{\sigma}).
\]

The goodness-of-fit test associated with pseudo-ML estimation is in turn defined as \( T_{ML} := n F_{ML}(\hat{\theta}) \), which corresponds to the Log-Likelihood Ratio test.
statistic for testing the model $\sigma = \sigma(\theta)$, against the general alternative in which the $\Sigma_\beta$ are unrestricted. Under normality, the statistics $T_R$, $T_{GLS}$ and $T_{ML}$ are asymptotically equivalent (i.e., they have the same asymptotic distribution as that stated above for $T_R$). Under non-normality of the $\Sigma_\beta$, $T_{GLS}$ and $T_{ML}$ are asymptotically equivalent, though not necessarily asymptotic chi-square. See Satorra (1989) for more details on the above goodness-of-fit test statistics, with discussion of their equivalence.

Under general distribution of the $\Sigma_\beta$, when the model holds exactly, $T_{GLS}$ and $T_{ML}$ are asymptotically distributed as a mixture of chi-square distributions of 1 degree of freedom (df) (see Satorra and Bentler, 1986); that is

$$T \xrightarrow{L} \sum_{j=1}^r \alpha_j \chi^2_j,$$

as $n \to \infty$, where $T$ denotes either of the statistics $T_{GLS}$ or $T_{ML}$. Here the $\chi^2_j$ are independent chi-square variables of 1 df, the $\alpha_j$ are the non-null eigen-values of the matrix $UT$, with

$$U := V - V \Delta J^{-1} \Delta' V,$$

$$J := \Delta' V \Delta \quad (= \sum_{j=1}^G f_j \Delta_j' \Sigma_j \Delta_j)$$

and $r := \text{rank}(\Delta_\perp' \Gamma \Delta_\perp)$. If the $\Sigma_\beta$ are normally distributed, then the $\alpha_j$ are equal to 1 and thus one obtains an asymptotic exact chi-square distribution for the goodness-of-fit test statistics. This result motivated the scaling correction to the goodness-of-fit test statistic proposed by Satorra and Bentler (1994; Satorra and Bentler, 1988a,b), the specialization of which to $T_{GLS}$ and $T_{ML}$ is as follows. Let

$$c := \frac{1}{r} \text{tr} \{ UT \} = \frac{1}{r} \text{tr} \left\{ V \Gamma - J^{-1} \Delta' V \Delta \right\}$$

$$= \frac{1}{r} \sum_{j=1}^G \text{tr} \left\{ V_\beta \Gamma_\beta - f_j J^{-1} \Delta'_\beta \Sigma_\beta \Delta_\beta J^{-1} \right\} = \frac{1}{r} \text{tr} \left\{ \left( \Delta'_\perp \Gamma \Delta_\perp \right)^{-1} \left( \Delta'_\perp \Gamma \Delta_\perp \right) \right\}$$

$$= \frac{1}{r} \text{tr} \left\{ \left( \sum_{j=1}^G f_j^{-1} H_j' V_j^{-1} H_j \right)^{-1} \left( \sum_{j=1}^G f_j^{-1} H_j' \Sigma_j H_j \right) \right\},$$

where $\Delta_\perp' = [H_1', \ldots, H_G']$ is partitioned conformably with the partition given above of $V$ as a block-diagonal matrix. From the expression (10) of a
consistent estimator of \( \Gamma \), a consistent estimator of \( c \) is
\[
\hat{c} := \sum_{g=1}^{G} \sum_{i=1}^{n_g} \frac{n}{n_g(n_g - 1)} (d_{gi} - s_g) \left\{ H_g \left( \sum_{g=1}^{G} \frac{n}{n_g} H_g' V_g^{-1} H_g \right)^{-1} H_g' \right\} (d_{gi} - s_g);
\]
(16)

thus, the scaled (adjusted for mean) goodness-of-fit test statistic is
\[
\overline{T} = T / \hat{c},
\]
(17)

where \( T \) denote either of the test statistics \( T_{GLS} \) or \( T_{ML} \).

We now discuss the adjusted test statistic (adjusted for mean and variance) introduced in structural equation models by Satorra and Bentler (1994; Satorra and Bentler, 1988a,b); viz.,
\[
\overline{T} = \frac{d}{\text{tr} (UT)} T,
\]

where \( d \) is the integer closest to
\[
d' := \frac{(\text{tr} UT)^2}{\text{tr} (UT)^2},
\]

and probability levels of \( \overline{T} \) computed using a chi-square distribution of \( d' \) degrees of freedom. The statistic \( \overline{T} \) is a Satterthwaite type test statistic (Satterthwaite, 1941). When tables from a chi-square distribution with fractional degrees of freedom are available, then \( d' \) is used instead of \( d \).

For the sake of completeness, we also review the asymptotic variance matrix of estimators. In the current set-up, the estimator \( \hat{\theta} \) is asymptotically normal with asymptotic variance matrix (e.g., Satorra and Neudecker, 1994)
\[
\text{avar}(\hat{\theta}) = n^{-1} J^{-1} \Delta' V TV \Delta J^{-1},
\]
(18)

where \( \Delta' V TV \Delta = \sum_{g=1}^{G} f_g \Delta_g V_g \Gamma_g V_g^T \Delta_g \). Obviously, standard errors of parameter estimators are produced by replacing population matrices for consistent estimators in the above formulae, and replacing the \( f_g \) by the \( \frac{n_g}{n} \). Clearly, when
\[
\Delta' V TV \Delta = \Delta' V \Delta,
\]
(19)

then \( \text{avar}(\hat{\theta}) = \text{avar}^*(\hat{\theta}) := n^{-1} J^{-1} \). Note that a sufficient condition for (19) to hold is
\[
V_g \Gamma_g V_g = V_g, \quad g = 1, \ldots, G,
\]
(20)

which is verified when the \( z_g \) are normally distributed.
3 Restricted tests

In this section we focus on testing a specific set of restrictions on the parameters of the model, when the alternative hypothesis is that the restrictions do not hold (rather than the general alternative that the $\Sigma_\delta$ are unrestricted).

Let us parameterise the fitted model $\sigma = \sigma(\theta)$ as $\sigma = \sigma^*(\delta)$ with the constraint $a(\delta) = a_0$, where $\delta$ is a $(q + m)$-dimensional vector of parameters, $a_0$ is an $m \times 1$ vector of constants, and $\sigma^*(.)$ and $a(.)$ are twice-continuously differentiable vector-valued functions of $\delta \in \Theta_1$, a compact subset of $\mathbb{R}^{q+m}$. Our interest is in testing $H_0 : a(\delta) = a_0$ against $H_1 : a(\delta) \neq a_0$. In multi-sample analysis, a typical example arises when testing across-sample invariance of model parameters (see the example in the illustration below).

Define the Jacobian matrices

$$
\Pi := (\partial/\partial \delta')\sigma^*(\delta) \quad \text{and} \quad A := (\partial/\partial \delta')a(\delta),
$$

which we assume to be regular at the value of $\delta$ associated with $\theta_0$, say $\delta_0$, with $A$ of full row rank. Let

$$
P := \Pi'\Pi \left( \sum_{g=1}^{G} f_g \Pi_g' V_g \Pi_g \right)
$$

and

$$
h' := (s - \hat{\sigma})' \hat{V} \hat{\Pi} \left( \sum_{g=1}^{G} \frac{n_g}{n} (s_g - \hat{\sigma}_g)' \hat{V}_g' \hat{\Pi}_g \right).
$$

Generalised score and Wald-test statistics for restricted tests were investigated by Satorra (1989, Section 5); viz., the generalised score test statistic is

$$
T_S := nh' \hat{P}^{-1} \hat{\Lambda} \left( \hat{\Lambda} \hat{P}^{-1} \Pi' \hat{V} \hat{\Gamma} \hat{V} \Pi \hat{P}^{-1} \hat{\Lambda} \right)^{-1} \hat{A} \hat{P}^{-1} h,
$$

where $\hat{\Lambda}$, $\hat{\Pi}$ and $\hat{P}$ are the matrices $A$, $\Pi$ and $P$ evaluated at $\hat{\theta}$, and $\hat{\Gamma}$ is the (distribution-free) consistent estimator of $\Gamma$ defined in (10).

Clearly, when

$$
\Pi' \Gamma V \Pi = \Pi' \Pi,
$$

i.e., when

$$
\sum_{g=1}^{G} \frac{n_g}{n} \Pi_g' \Pi_g \Gamma_g \Pi_g = \sum_{g=1}^{G} \frac{n_g}{n} \Pi_g' \Pi_g,
$$

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then $T_S$ is asymptotically equivalent to the (non-robust, asymptotically) score test statistic

$$T^*_S := n h' \hat{P}^{-1} \hat{A}' (\hat{A} \hat{P}^{-1} \hat{A}')^{-1} \hat{A} \hat{P}^{-1} h.$$ 

The statistic $T^*_S$ is asymptotic chi-square under the condition that the estimation method is asymptotically optimal (Satorra, 1989). Specifically, when $V$ has the normal-theory form given above and the $z_{gi}$ are normally distributed, then $T^*_S$ corresponds to the usual score test statistic. In the case of one-dimensional restrictions, $T^*_S$ is the “Modification Index” of Jöreskog and Sörbom and Sörbom (1989). $T^*_S$ is the “Lagrange Multiplier” test available in EQS (Bentler, 1995) for general multi-dimensional restrictions.

When the fitted model is the less restricted one, that is when the model analysed is $\sigma = \sigma^*(\hat{\delta})$, then the generalised Wald-test statistic for $H_0 : a(\hat{\delta}) = a_0$ against $H_0 : a(\hat{\delta}) \neq a_0$ is (see Satorra, 1989, Section 5)

$$T_W := n \hat{\sigma}' \left( \hat{A} \hat{P}^{-1} \hat{V}' V \hat{P}^{-1} \hat{A}' \right)^{-1} \hat{a},$$

where the matrices are now evaluated at the estimated value $\hat{\delta}$ under the unrestricted model and $\hat{a} := a(\hat{\delta})$. When $\hat{V}' V = J$, then $T_W$ is asymptotically equivalent to the (non-robust, asymptotically) Wald-test statistic

$$T^*_W := n \hat{\sigma}' \left( \hat{A} \hat{P}^{-1} \hat{A}' \right)^{-1} \hat{a}.$$ 

Under the assumption of normality of the $z_{gi}$, when we use ML or normal-theory GLS estimation methods then $T^*_W$ is the typical Wald-test statistic.

When both the restricted and unrestricted models are analyzed using GLS or ML estimation methods, the restricted test of $H_0 : a(\delta) = a_0$ can be carried out using the difference-test statistic

$$DT := T_0 - T_1,$$

where $T_0$ and $T_1$ denote the goodness-of-fit test statistics ($T_{GLS}$ or $T_{ML}$) associated with the restricted and unrestricted models respectively. Under an arbitrary distribution of the observable variables, the three test statistics $T^*_S$, $T^*_W$ and $DT$ are asymptotically equivalent (see Satorra, 1989, Theorem 4.1), though not necessarily chi-square distributed; when the estimation method is asymptotically optimal, then all the statistics $T^*_S$, $T^*_W$, $DT$, $T_S$ and $T_W$ are asymptotically equivalent, with the same asymptotic chi-square distribution (Satorra, 1989).
We will now obtain the expression of $T_S$ and $T_2^*$ for the particular case in which $a(\delta) = a_0$ corresponds to equating parameters to specific values; in this case, without loss of generality, we have $A = [0_{m \times q}, I_m]$ and $h' = [0_{1 \times q}, h'_2]$; consequently,

$$h' \hat{P}^{-1} \hat{A}' = h'_2 \hat{P}^{22} \quad \text{and} \quad (\hat{A} \hat{P}^{-1} \hat{A}')^{-1} = (\hat{P}^{22})^{-1} = \hat{P}_{22} - \hat{P}_{21} \hat{P}_{11}^{-1} \hat{P}_{12},$$

where we used

$$\hat{P} := \begin{pmatrix} \hat{P}_{11} & \hat{P}_{12} \\ \hat{P}_{21} & \hat{P}_{22} \end{pmatrix} \quad \text{and} \quad \hat{P}^{-1} := \begin{pmatrix} \hat{P}_{11} & \hat{P}_{12} \\ \hat{P}_{21} & \hat{P}_{22} \end{pmatrix}^{-1}$$

(partitions corresponding to $h' = [0_{1 \times q}, h'_2]$), and standard formulae for the inverse of partitioned matrices (e.g., Magnus and Neudecker, 1999, p.11). Consequently,

$$T_S = nh'_2 \hat{P}^{22} \left\{ \left( \hat{P}^{21}, \hat{P}^{22} \right) \hat{H}' \hat{V} \hat{V} \hat{H} \left( \hat{P}^{22} \hat{P}^{22} \right) \right\}^{-1} \hat{P}^{22} h'_2$$

$$= nh'_2 \left\{ \left( -\hat{P}_{21} \hat{P}_{11}^{-1}, I_m \right) \hat{H}' \hat{V} \hat{V} \hat{H} \left( -\hat{P}_{11}^{-1} \hat{P}_{12} \right) \right\}^{-1} h'_2,$$

where we used $\hat{P}^{21} = -\hat{P}_{21} \hat{P}_{11}^{-1}$ and $(\hat{P}^{21})' = \hat{P}^{12}$. Similarly, we can express $T_2^*$ as

$$T_2^* = nh'_2 \hat{P}^{22} (\hat{P}^{22})^{-1} \hat{P}^{22} h'_2$$

$$= nh'_2 (\hat{P}_{22} - \hat{P}_{21} \hat{P}_{11}^{-1} \hat{P}_{12})^{-1} h'_2.$$ 

Note that $h_2$ corresponds to the components of $h$ that are not equal to zero when evaluated at the restricted parameter value $\hat{\theta}$. Note also that $\hat{P}_{11}^{-1}$ is the “information” matrix associated with the restricted model, and it does not change with the restrictions being tested.

The SB scaled versions of $T_S$, $T_W$, and $DT$ will thus be obtained by dividing the corresponding statistic by a consistent estimate of $c$ in (15), where $\hat{U}$ is now given by (cf., Satorra 1989, p. 146)

$$U = V H P^{-1} A'(A P^{-1} A')^{-1} A P^{-1} H' V,$$

(22)

with $m$ (the number of rows of $A$) replacing $r$; that is, the scaled statistic is

$$\hat{T} := T / \hat{c},$$

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where here $T$ denotes any of the statistics $T_S^r$, $T_W^r$ and $DT$, $\hat{c} = \frac{1}{m} \text{tr} \hat{U} \hat{T}$ and $\hat{U}$ is the matrix $U$ of (22) with the matrices $\Pi$, $P$ and $A$ evaluated at estimated values, and $\hat{V}$ replaces $V$.

We will now obtain an explicit expression for $c$ in the case of restricted tests and multi-samples. Clearly,

$$c = \frac{1}{m} \text{tr} UT = \frac{1}{m} \text{tr} \left( AP^{-1} \Pi VTV \Pi P^{-1} A' \right) \left( AP^{-1} A' \right)^{-1} \tag{23}$$

$$= \frac{1}{m} \text{tr} \left( VTV \right) \left\{ \Pi P^{-1} A' \left( AP^{-1} A' \right)^{-1} AP^{-1} \Pi' \right\}$$

$$= \frac{1}{m} \sum_{g=1}^{G} f_g \text{tr} \left( V_g \Gamma_g V_g \right) \left\{ \Pi_s P^{-1} A' \left( AP^{-1} A' \right)^{-1} AP^{-1} \Pi_s' \right\},$$

where $\Pi_g := (\partial / \partial \delta') \sigma_g^2 (\delta)$. Note that this scaling factor does not necessarily coincide with the scaling factor associated with $T_0$, nor with that associated with $T_1$; i.e., the SB scaled $DT$ is not the difference of the SB scaled goodness-of-fit tests $T_1$ and $T_0$.

We now show that when $m = 1$, then the scaled score statistic $T_S^r (= T_S^r / \hat{c})$ coincides with the robust score statistic $T_S$. When $m = 1$, the scaling factor $c$ defined above is

$$c = \frac{AP^{-1} \Pi VTV \Pi P^{-1} A'}{AP^{-1} A'}, \tag{24}$$

and the robust and non-robust score statistics can be be expressed as

$$T_S = n - \frac{k' \hat{P}^{-1} \hat{A}' \hat{A} \hat{P}^{-1} h}{AP^{-1} \Pi VTV \Pi P^{-1} A'} \tag{25}$$

and

$$T_S^r = n - \frac{k' \hat{P}^{-1} \hat{A}' \hat{A} \hat{P}^{-1} h}{AP^{-1} A'} \tag{26}$$

Consequently, we have

$$T_S = T_S^r / \hat{c}, \tag{27}$$

where

$$\hat{c} = \frac{\hat{A} \hat{P}^{-1} \Pi VTV \Pi \hat{P}^{-1} \hat{A}'}{AP^{-1} A'}, \tag{28}$$

is a consistent estimator of the SB scaling factor $c$ of (23). Moreover, if in addition to $m = 1$ we have that $a(\delta) = a_0$ restricts a parameter to a
specific value, then $\hat{c}$ of (28) is the ratio of two standard errors of the restricted parameter: the asymptotic robust standard error (computed from (18), unrestricted model), and the NT standard error (computed from $J^{-1}$, unrestricted model).

We now provide an explicit expression for $c$ when $A = [0_{m \times q}, I_m]$. In this case we have

$$c = \frac{1}{m} \text{tr} VTV \left\{ P^{-1} A' (AP^{-1} A')^{-1} AP^{-1} \right\} \Pi'$$

$$= \frac{1}{m} \text{tr} VTV \left\{ \left( \begin{array}{cc} \hat{P}^{21} & \hat{P}^{22} \\ \hat{P}^{21} & \hat{P}^{22} \end{array} \right) \left( \begin{array}{c} \hat{P}^{12} \\ \hat{P}^{22} \end{array} \right)^{-1} \right\} \Pi' = \frac{1}{m} \text{tr} VTV \Pi M \Pi'$$

where

$$M := \left( \begin{array}{cc} P^{12} (P^{22})^{-1} P^{21} & P^{12} P^{21} \\ P^{21} & P^{22} \end{array} \right) = \left( \begin{array}{ccc} P_{11}^{-1} P_{12} & P_{22}^{12} P_{21} & P_{22}^{-1} P_{12} P_{22} \\ -P_{22} P_{21} P_{11}^{-1} & P_{22} P_{21} P_{11}^{-1} & P_{22} P_{21} P_{11}^{-1} \\ P_{22} P_{21} P_{11}^{-1} & P_{22} P_{21} P_{11}^{-1} & P_{22} P_{21} P_{11}^{-1} \end{array} \right).$$

Finally, the specialization of the SB adjusted (for mean and variance) goodness-of-fit test to $T_S^\ast$, $T_W^\ast$ and $DT$ test statistics is as follows. We define

$$\overline{T} := (d' \text{tr} \hat{U} \hat{\Gamma}) T,$$

where $T$ denotes any of the statistics $T_S^\ast$, $T_W^\ast$ or $DT$, and $d$ is the integer closest to

$$d' := \frac{\left( \text{tr} \hat{U} \hat{\Gamma} \right)^2}{\text{tr} (\hat{U} \hat{\Gamma})^2},$$

with $\hat{U}$ being the matrix of (22) evaluated at estimated values, and $\hat{\Gamma}$ given in (10). The null distribution of the adjusted test statistic $\overline{T}$ is taken to be a chi-square distribution with $d$ degrees of freedom. Here $d'$ also replaces $d$ when tables of a chi-square distribution with fractional degrees of freedom are available.

4 Illustration

To illustrate the performance of the above statistics in finite samples, a specific model context is used to simulate the competing score-test statistics introduced in the previous section for various sample sizes. The performance
of the test statistics is evaluated by comparing Monte Carlo rejection frequencies with the corresponding nominal values.

We use a very simple model context. We consider a regression equation

\[ y^*_{gi} = \beta x_{gi} + v_{gi}, \quad i = 1, \ldots, n_g, \quad (29) \]

where for case \( i \) in group \( g \) \((g = 1, 2)\), \( y^*_{gi} \) and \( x_{gi} \) are the values of the response and explanatory variables, respectively, \( v_{gi} \) is the value of the disturbance term, and \( \beta \) is the regression coefficient. The model assumes that \( x_{gi} \) is unobservable, but there are two observable variables \( x^*_{1gi} \) and \( x^*_{2gi} \) related to \( x_{gi} \) by the following measurement-error equations

\[ x^*_{1gi} = x_{gi} + u_{1gi}, \quad x^*_{2gi} = x_{gi} + u_{2gi}, \quad (30) \]

where \( u_{1gi} \) and \( u_{2gi} \) are mutually independent and also independent of \( v_{gi} \) and \( x_{gi} \). It is assumed that the observations are independent and identically distributed within each group. Equations (29) and (30) with the associated assumptions yield an identified model (see Fuller (1987) for a comprehensive overview of measurement-error models in regression analysis). Inference is usually carried out in this type of model under the assumption that the observable variables are normally distributed.

Write the model of (29) and (30) as

\[ z_{gi} = \Lambda \xi_{gi}, \quad i = 1, 2, \ldots, n, \quad (31) \]

where

\[ z_{gi} := \begin{pmatrix} y^*_{gi} \\ x^*_{1gi} \\ x^*_{2gi} \end{pmatrix}, \quad \xi_{gi} := \begin{pmatrix} x_{gi} \\ v_{gi} \\ u_{1gi} \\ u_{2gi} \end{pmatrix} \]

and

\[ \Lambda := \begin{pmatrix} \beta & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{pmatrix}. \quad (32) \]

Define

\[ \Phi := E \xi_{gi} \xi_{gi}' = \begin{pmatrix} \sigma_{xx} & 0 & 0 & 0 \\ 0 & \sigma_{uv} & 0 & 0 \\ 0 & 0 & \sigma_{uu} & 0 \\ 0 & 0 & 0 & \sigma_{uu} \end{pmatrix}, \quad (33) \]
and the parameter vector \( \theta := (\sigma_{vv}, \sigma_{xx}, \sigma_{ux}, \beta)' \). Under this set-up, we obtain the moment structure
\[
\Sigma := \Lambda \Phi' \Lambda = \Sigma(\theta),
\]
where \( \Sigma(\cdot) \), \( \Lambda(\cdot) \) and \( \Phi(\cdot) \) are (twice-continuously differentiable) matrix-valued functions of \( \theta \), as deduced from (32), (33) and (34). Note that the model restricts the variances of \( u_1 \) and \( u_2 \) by equality.

The simulation of two-sample data from the above model and computation of score test statistics was replicated 1000 times, for various combinations of two-sample sizes as shown in Table 1. In all the replications we used \( \theta_0 = (1, 1, 3, 2)' \). The distributions of \( v \) and \( x \) were independent conveniently scaled zero mean and unit variance chi-squared of 1 df (i.e., a highly non-normal distribution); the distribution of \( u_1 \) and \( u_2 \) were set to be normal mutually, independent, and independent of \( v \) and \( x \). The normal-theory GLS estimation method described in Section 2 was used. The model imposed across-group invariance of model parameters. In each replication, we computed the various versions of the score-test statistic of Section 3, for the null hypothesis of across-group invariance of all model parameters. Clearly, in our Monte Carlo set-up, the null hypothesis holds true, with the asymptotic distribution of \( T_S \) being chi-square with \( m = 4 \) degrees of freedom. Note that in our Monte Carlo set-up, severe non-normality of random constituents of the model requires the use of robust and/or corrected versions of the score-test statistic.

We note that the normal-theory chi-square goodness-of-fit \( T_1 \) \((T_{GLS} \text{ or } T_{ML}) \) of the unrestricted model (i.e. the model that does not restrict parameters across-groups), is an asymptotic chi-square statistic despite non-normality of the data (this follows from the asymptotic robustness theory for multi-sample; cf., Satorra, 1993); in contrast, the normal-theory chi-square goodness of fit \( T_0 \) of the restricted model (i.e., the model that imposes parameter invariance across-samples), is not necessarily an asymptotic chi-square statistic (since variances of non-normal constituents of the model are restricted by equality across-groups; cf., Satorra, 1993). Consequently, since \( DT := T_1 - T_0 \) is asymptotically equal to \( T_S^2 \) (Satorra, 1989), the scaling factor \( c \) for \( T_S^2 \) does not need to coincide with the scaling factor \( c \) associated with \( T_1 \) (which is 1, as deduced from the mentioned theory of asymptotic robustness), nor with the scaling factor \( c \) associated to \( T_0 \).

As shown in Table 1, in our specific model context, in the case of small
samples, the SB scaled statistic, $\overline{T_S}$, seems to outperform the alternative robust test statistic $T_S$. As expected from theory, in the case of large samples, $T_S$ outperforms the alternative test statistics. The adjusted test statistic, $\overline{T_S}$, shows acceptable performance in various sample sizes. Clearly, the normal-theory score-test statistic $\overline{T_S}$ performs very poorly for all sample sizes considered in this Monte Carlo study.

References


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[23] Satterthwaite, F.E., (1941), Synthesis of Variance, Psychometrika, 6, 309–316.

